

# Niladri Das

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RESEARCH

- **Nonlinear estimation**
- **Situational awareness**
- **Optimal sensing and data sharing**
- **Nonlinear control, robotics, and machine learning**

EDUCATION Doctor of Philosophy in **Aerospace Engineering** Adviser: [Dr. R. Bhattacharya](#)  
Texas A&M University, USA 2015 - 2020  
**Dissertation:** Optimal sensing for estimation of nonlinear dynamical systems. GPA: 3.826

Master of Technology in **Electrical Engineering** Adviser: [Dr. L. Behera](#)  
Indian Institute of Technology Kanpur (IIT-K), India 2012 - 2014  
**Dissertation:** Learning to grasp & programming by demonstration using a 7-DOF [Barrett WAM](#). GPA : 7.91/10

Bachelor of Engineering in **Electrical Engineering** Adviser: Dr. A. Chatterjee  
Jadavpur University, Kolkata, India 2008 - 2012  
**Project:** Image processing based object detection. GPA : 7.84/10

RESEARCH **Graduate Research Assistantship** at TAMU Adviser: Dr. K. DeMars, Summer 2020  
EXPERIENCE — Information filter

**Graduate Research Assistantship** at TAMU Adviser: Dr. R. Bhattacharya  
— Worked on optimal sensing for nonlinear filters from utility and privacy perspective  
— Worked on an [AFRL](#) project project: *Adaptive Markov Inference Game Optimization for Rapid Discovery of Evasive Satellite Behaviors*, in collaboration with Intelligent Fusion Technology, Inc., where I developed an in-house orbit propagator. (2018-2019)  
— Worked on an AFOSR project: *Cloud Computing Based Robust Space Situational Awareness (SSA)*, in collaboration with Dept. of Statistics (TAMU), where I developed Optimal Transport filter based framework for SSA. (2015-2018)

**Project Associate** at IIT-K PI: Dr. L. Behera, Aug 2014 - Jun 2015  
— Developed Gaussian Mixture based model to compensate the unknown non-linearities of 7 degree of freedom [Barrett WAM](#).  
— Collaborated in implementing a inverse kinematic model and higher order Sliding Mode Control for 7 degree of freedom Barrett WAM. [\[C++ codes\]](#)[\[video\]](#)  
— Developed dynamical system based trajectory learning for Barrett WAM.  
— Served as a Thesis mentor for a master's student.  
— Taught ROS to two Master's student.

**Graduate Research Assistant** at IIT-K Adviser: Dr. L. Behera, July 2013-July 2014  
— Developed Inverse Kinematic model for Barrett WAM.  
— Implemented Kinect based Object segmentation for grasping using **Deep Learning**.  
— Developed a hand-eye autonomous calibration technique for Barrett WAM.

- Implemented Symbolic Encoding based skill learning on Barrett WAM.[[video](#)]
- Mentored two Under-Graduate interns.

PUBLICATIONS *Journals*

1. **Privacy-Utility Aware Kalman Filtering for LTI Systems** [preparing, 2020]
2. **Optimal Sensor Precision and Sensor Selection for Kalman Filtering with Bounded Errors** | Signal Processing, Elsevier [under review, 2020]
3. **Privacy and Utility Aware Data Sharing for Space Situational Awareness from Ensemble and Unscented Kalman Filtering Perspective** | IEEE Transactions on Aerospace and Electronic Systems [under review, 2019][[arXiv](#)]
4. **Optimal Transport Based Tracking of Space Objects in Cylindrical Manifolds** | Journal of Astronautical Sciences, Springer [2019][[preprint](#)]
5. **Optimal Transport based Tracking of Space Objects using Range Data from a Single Ranging Station** | Journal of Guidance, Control, and Dynamics [2019][[preprint](#)]

*Conferences*

1. **Utility and Privacy in Object Tracking from Video Stream using Kalman Filter** | International Conference on Information Fusion 2020 [accepted]
2. **Modeling and Optimal Control of Hybrid UAVs with Wind Disturbance** | International Conference on Systems and Control 2020 [second author][accepted]
3. **Eigen Value Analysis in Lower Bounding Uncertainty of Kalman Filter Estimates** | IFAC World Congress 2020 [accepted]
4. **Optimal Transport Based Filtering with Nonlinear State Equality Constraints** | IFAC World Congress 2020 [accepted]
5. **Optimal Sensing Precision in Ensemble and Unscented Kalman Filtering** | IFAC World Congress 2020 [accepted]
6. **On Neural Network Training from Noisy Data using a Novel Filtering Framework** | AIAA SciTech Forum and Exposition 2020 [second author]
7. **Sparse Sensing Architecture For Kalman Filtering With Guaranteed Error Bound.** | IAA Conference on Space Situational Awareness 2017
8. **Control of a 4 DoF Barrett WAM Robot - Modeling, Control Synthesis and Experimental Validation** | IEEE First International Conference on Control, Measurement and Instrumentation 2016 [second author]
9. **Learning Object Manipulation from Demonstration through Vision for the 7-DOF Barrett WAM** | IEEE First International Conference on Control, Measurement and Instrumentation 2016
10. **A probabilistic framework of learning movement primitives from unstructured demonstrations** | IEEE 13th International Conference on Industrial Informatics 2015
11. **Robot Learns from Human Teacher Through Modified Kinesthetic Teaching** | International conference on Advances in Control and Optimization of Dynamic Systems 2014

TEACHING  
EXPERIENCES

**Graduate Teaching Assistant** at TAMU Aug - Dec 2020  
 Assisting Dr. Raktim Bhattacharya with AERO-310  
 Assisting Dr. Shinivas Rao Vadali with AERO-422

**Graduate Teaching Assistant** at TAMU 13 Jan - May 2020  
 Assisting [Dr. Kyle DeMars](#) for grading assignments for *Advanced Control for Aerospace Vehicles*

**Graduate Teaching Fellow** at TAMU

26 Aug - 12 Dec 2019

Taught *Advanced Control for Aerospace Vehicles* to senior Aerospace undergrads (72 students).

Taught LTI system, PID, root locus and freq. domain based controller design using Matlab.

**Graduate Teaching Assistant** at IIT-K

July 2012 - July 2014

Assisting Dr. L. Behera, Dr. R. Potluri, and Dr. N. K. Verma

**SKILLS**      *Programming Languages and Packages:* Matlab | Python | Julia | ROS | C++.

**CURRENT**      — American Institute of Aeronautics and Astronautics

**PROFESSIONAL** — Institute of Electrical and Electronics Engineers

**AFFILIATIONS** — Society for Industrial and Applied Mathematics

— American Astronautical Society

**PAST**            — Student Council member of Aerospace Engineering department at TAMU (2017)

**AFFILIATIONS** — Graduate and Professional Student Council department delegate at TAMU (2017)

**SERVICES**     **Journal Reviewer:** IEEE Systems Journal

**Conference Reviewer:** IFAC World Congress, CDC

**AWARDS**        — Winner of A-Hack-of-the-Drones (28-30 Sep 2018)

Member of the **A-Team** from Texas A&M that won the [A-Hack-of-the-Drones](#) competition (Sponsor: USArmy Futures Command and MD5) in Austin, Texas. We developed vision based solution for C-SUAS and co-founded AIMS Technologies, LLC

— Awarded Graduate Teaching Fellowship for Fall 2019 at TAMU

— Awarded AERO Graduate Excellence Fellowship for Fall 2019 and Spring 2020 at TAMU

— Awarded AERO Travel Grant for Spring 2019 at TAMU

**HONORS**        Served as a Student Council **Mentor** of Aerospace Engineering Department at TAMU (2018)

**WORK PERMIT** **F1 Visa** — Eligible to work in the USA for 36 months with Optional Practical Training

**PRIMARY**        — Dr. Raktim Bhattacharya (Dissertation Advisor)

**REFEREE**        Associate Professor, Department of Aerospace Engineering

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— Dr. Srinivas Rao Vadali (PhD Committee Member)

Professor, Department of Aerospace Engineering

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— Dr. Suman Chakravorty (PhD Committee Member)

Associate Professor, Department of Aerospace Engineering

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— Dr. Vikram Kinra (Director of Teaching Fellows Program)

Professor, Department of Aerospace Engineering

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